

Refractivity and EM Waves

• Refractive index *n*

$$n = \frac{\text{Speed of Light in Vacuum}}{\text{Speed of Light in the Medium}}$$
Near the surface, $n \approx 1.0003$

Refractivity

$$N = 10^6 (n-1)$$

Refractivity, Moisture, and Temperature

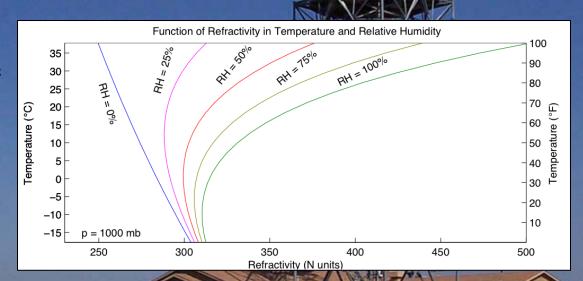
• Refractivity:

$$N = 77.6 \frac{p}{T} + 3.73 \times 10^5 \frac{e}{T^2}$$

p = air pressure

T = air temperature

e = vapor pressure





Refractivity and EM Waves

■ Travel time changes with refractive index

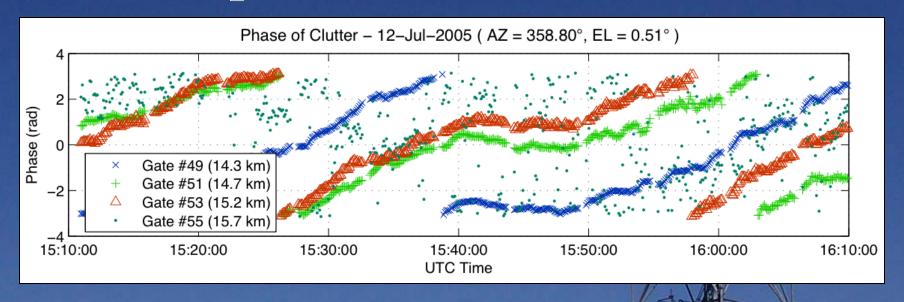
$$t_{\rm travel} = 2r \frac{n}{c}$$

Refractive index is translated into radar phase

$$\phi(r) = 2\pi f t_{travel} = rac{4\pi}{\lambda} \int_0^r n(\gamma) d\gamma$$

- Radar phase from stationary ground clutter (constant *r*) should have constant phase if refractivity remains constant
- Moving targets cannot be used with current algorithm

Example Phase Measurements



- Can we measure refractive index by using radar phase?
- Use phase difference from multiple ground targets along same radial for range resolution.
- For S-band radars, the phase wraps very quickly with increasing range (every 5cm!)

Solution to Rapid Phase Wrap

[Fabry, JTECH, 21, pp. 560-573, 2004]

 Use phase difference between two measurements in time for same clutter points.

$$\Delta \phi = \phi(t_1) - \phi(t_0) = \frac{4\pi}{\lambda} \int_0^r \left[n(\gamma, t_1) - \phi(x, t_0) \right] d\gamma$$

Results in slow phase wrap with range (~1-3 km)

- Use measurement at t_0 as reference
 - Take reference phase measurement when refractivity is homogeneous over the entire field (*could be days*, *or even months*, *apart from observational time*)
 - A closely-spaced network of surface stations (Mesonet)
 can be used to validate this condition.

Phase Difference to Refractivity

• With ϕ_{ref} and n_{ref} measured from a day with homogeneous refractivity

$$\frac{d}{dr} \left[\phi(t) - \phi_{\text{ref}} \right] = \frac{4\pi f}{c} \left[n(r, t) - n \right]$$

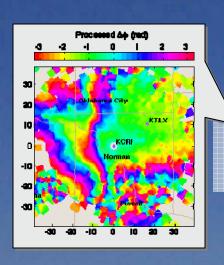
$$\Delta n(r, t) = \frac{c}{4\pi f} \frac{d}{dr} \left[\phi(t) - \phi_{\text{ref}} \right]$$

$$n(r, t) = \frac{c}{4\pi f} \frac{d}{dr} \left[\phi(t) - \phi_{\text{ref}} \right] + n_{\text{ref}}(r)$$

Overview of Refractivity Retrieval Algorithm

Phase measurement for a map of reference phase

Phase measurement during operational time

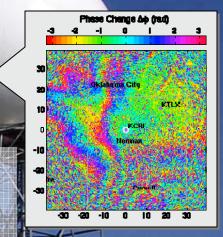


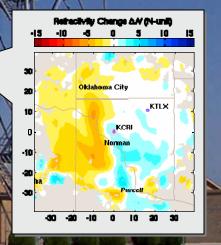
A map of Phase Difference: $\triangle \phi$

Image Processing: Clutter Quality, Masking, □Smoothing

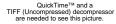
Radial gradient $\rightarrow \triangle N$

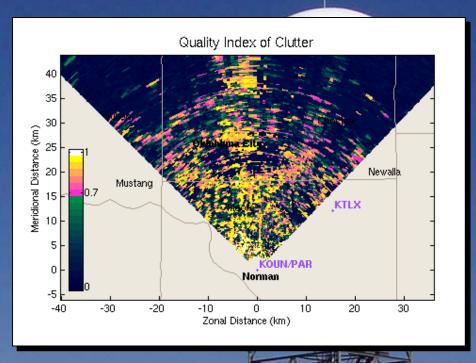
$$\Delta n(r,t) = rac{c}{4\pi f}rac{d}{dr}\left[\phi(t)-\phi_{
m ref}
ight]_{(r)}$$





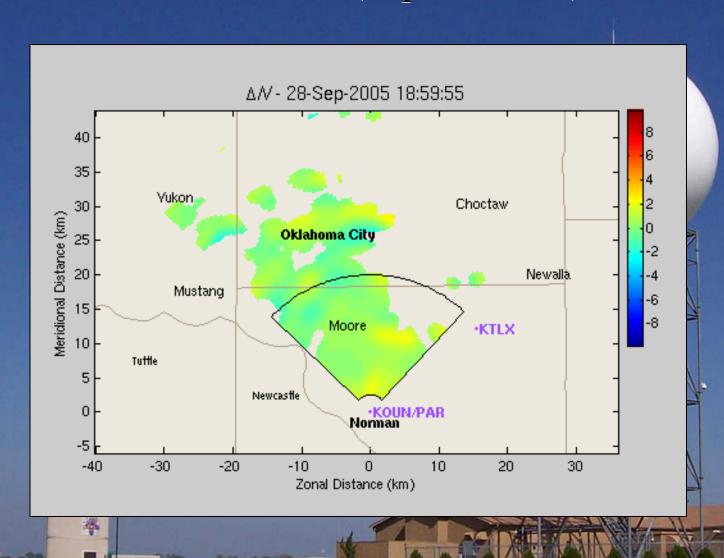
National Weather Radar Testbed Phased Array Radar





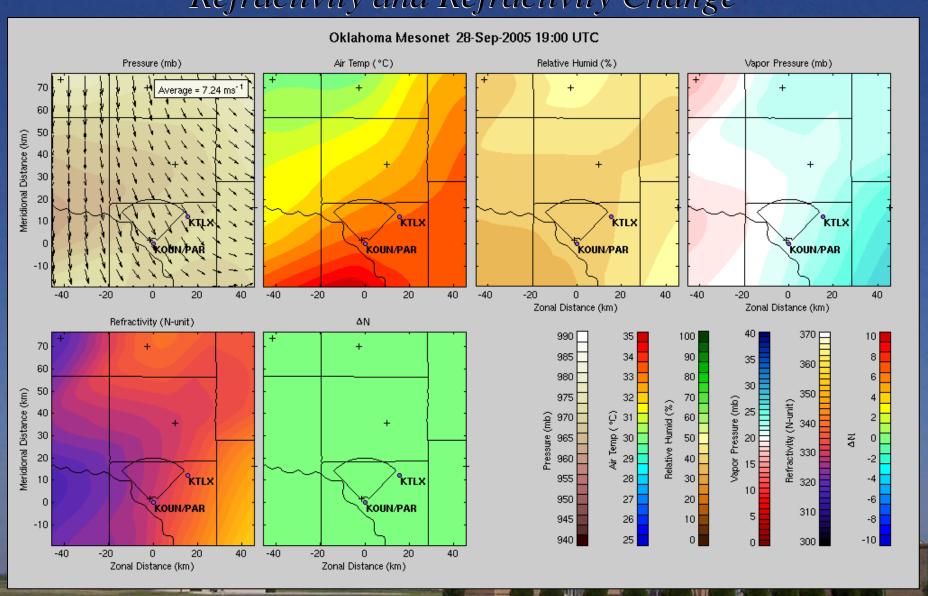
- Operated by NSSL
- SPY-1A Technology
- An array of 4352 elements
- S-band transmitter, 90° coverage

Refractivity *Change*NWRT-PAR (Sept 28, 2005)

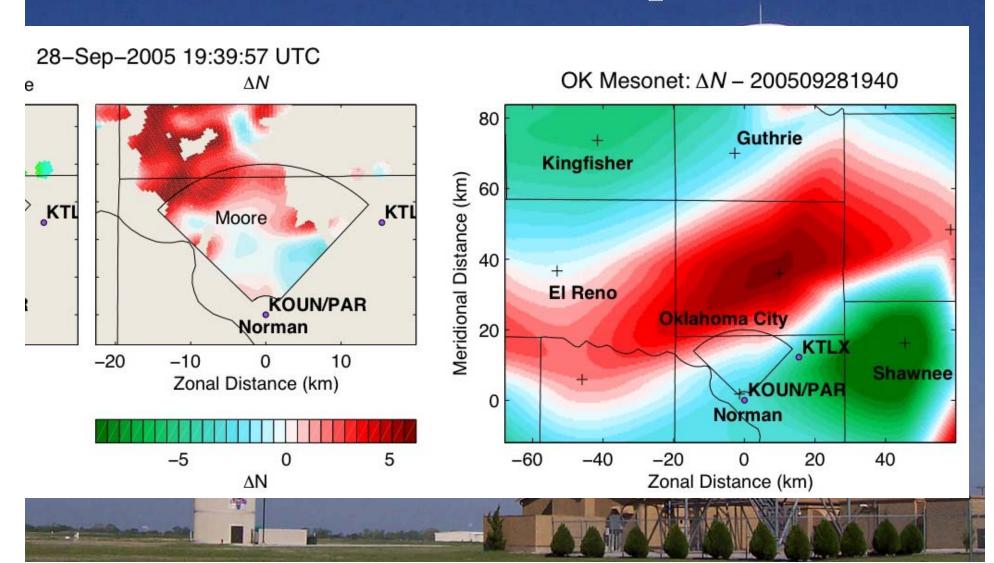


Oklahoma Mesonet

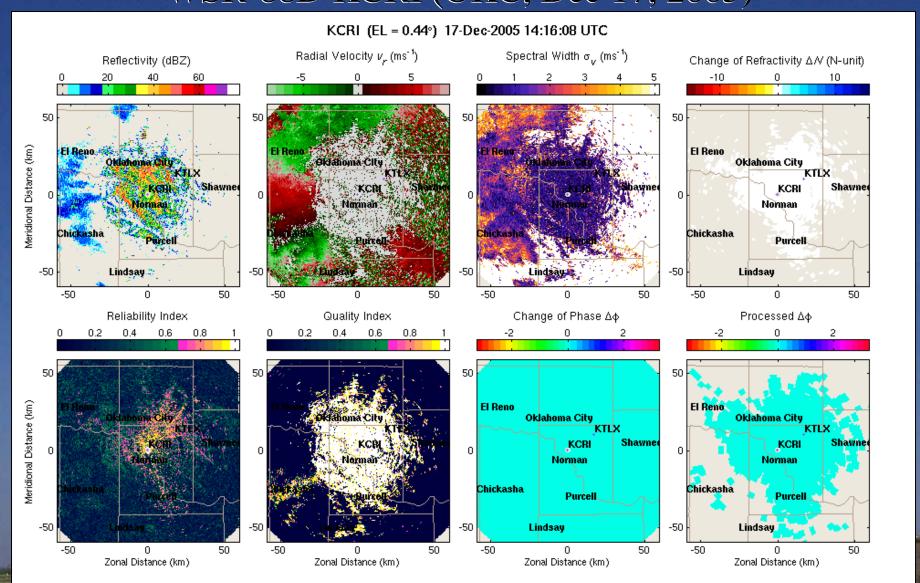
Refractivity and Refractivity Change



PAR/Mesonet Comparison

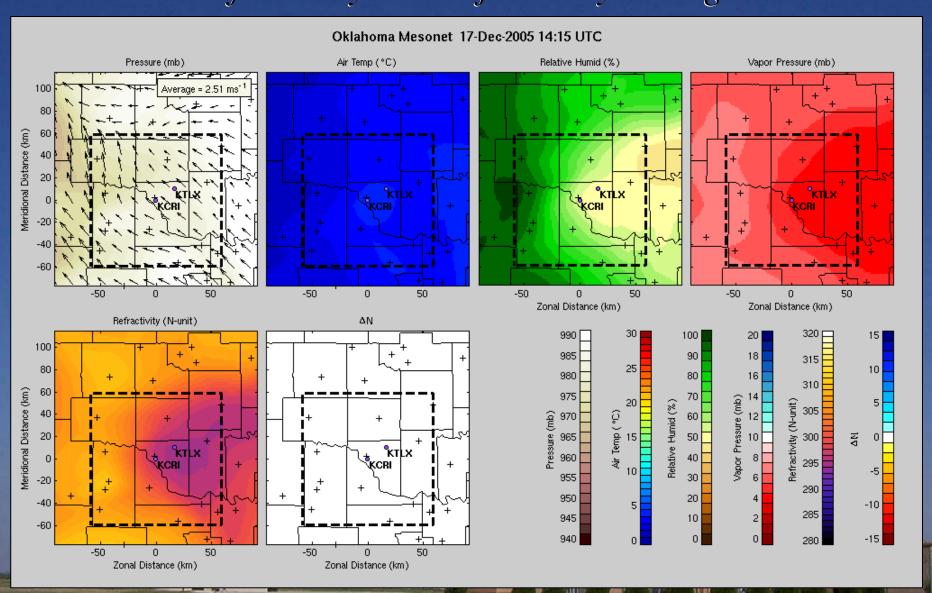


Refractivity *Change*WSR-88D KCRI (OKC, Dec 17, 2005)

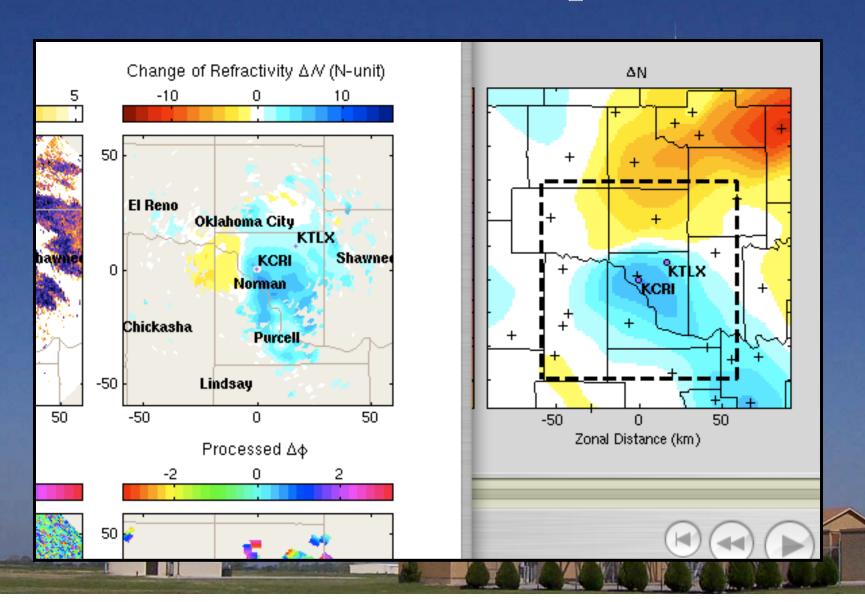


Oklahoma Mesonet

Refractivity and Refractivity Change



KCRI/Mesonet Comparison



Solution to X-Band Phase Wrap

Differential Refractivity Retrieval (DRR)

■ Use *phase difference* between two measurements in time (*between scans k*) for same clutter points. Between scans, phase difference is extremely small and unlikely to wrap.

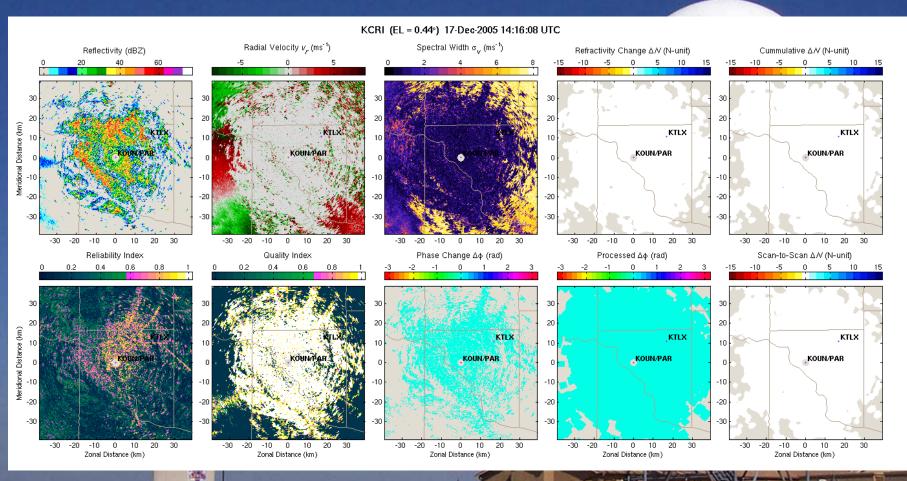
$$\Delta \phi_k = \phi(t_k) - \phi(t_{k-1}) = \frac{4\pi}{\lambda} \int_0^r \left[n(\gamma, t_k) - n(\gamma, t_k) \right] d\gamma$$

Implement an iterative sum of differential phase measurements to *track* the desired cumulative phase change

$$\Delta \phi = \sum_{k=1}^{K} \Delta \phi_k = [\phi(t_1) - \phi(t_0)] + [\phi(t_2) - \phi(t_1)] + \dots + [\phi(t_K) - \phi(t_K) - \phi(t_K)] + \dots + [\phi(t_K) -$$

Results in simple phase unwrapping, even for X-band wavelengths

DRR Implementation Simulated KCRI X-Band Results





Mitigation of Non-Stationary Clutter

From Wind Turbine Farms

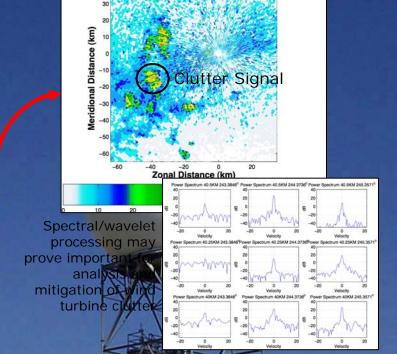
•Renewable energy production is becoming increasing important due in part to economic, political, and environmental concerns

•Wind farms cause non-stationary clutter signals and wake turbulence-induced radar echoes, adversely affecting the operation of military, air traffic, and weather surveillance radars

•Conventional ground clutter filters are ineffective for mitigating clutter signals from rotating blades



Gray County Wind Farm - 170 turbines (near Dodge City, Kansas)



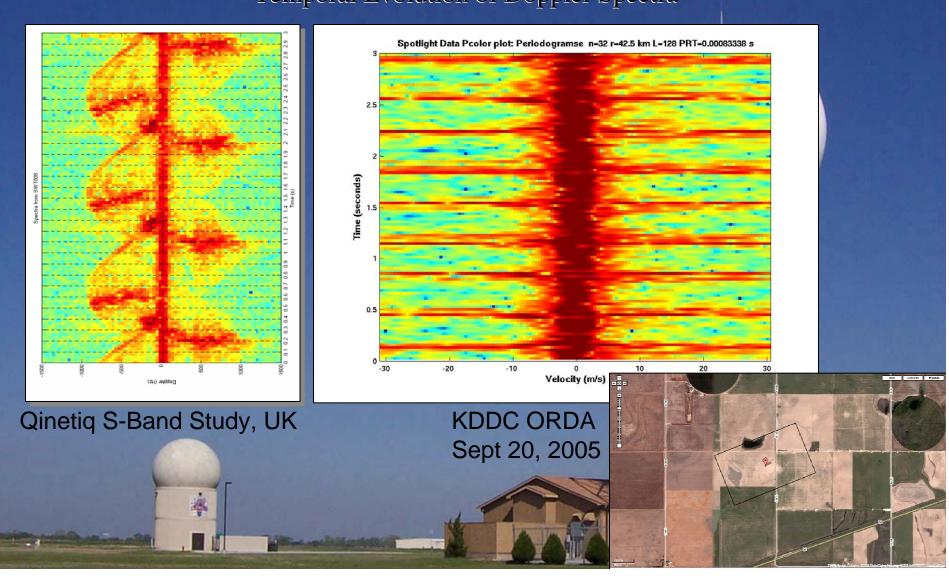
Reflectivity (dBZ)

Future Project Using CASA Radars

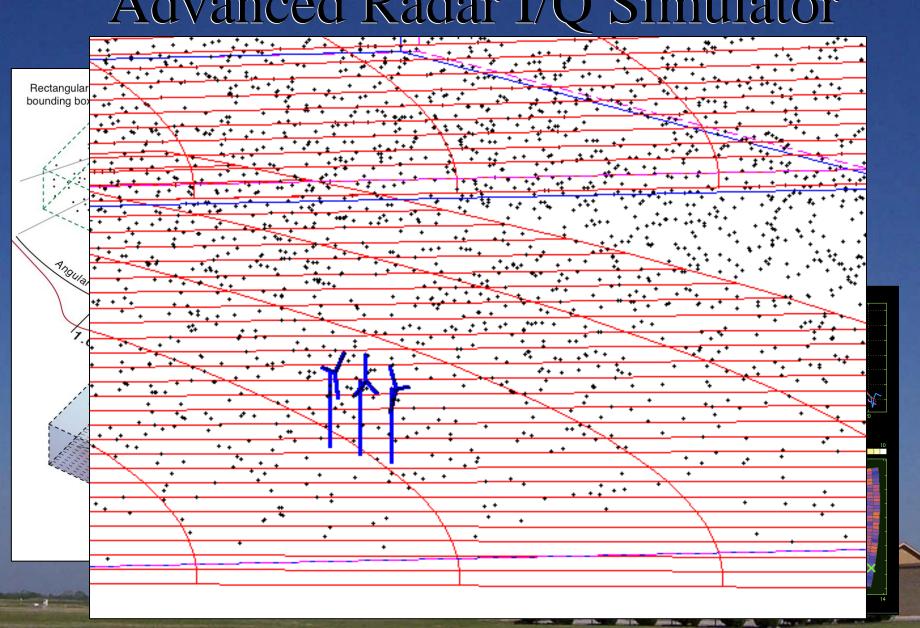


Wind Turbine Signature

Temporal Evolution of Doppler Spectra



Advanced Radar I/Q Simulator



Near-Term Plans

Wind Turbine Clutter Project

- Continue to improve the turbine model used in simulation for better understanding of the Wind Turbine Radar Signature
- Collect new set of Level-I data with recently installed ORDA at KDDC
 - Spotlight Mode
 - 2-3 azimuth angles
 - Highest PRF (1304 Hz)
 - 250 m range resolution with 25 m range sampling
 - Simultaneous visual observations of turbine orientation, rotation rate, etc.
 - Collaboration with wind farm managers?
 - Scanning Mode
 - Allow more realistic experimental conditions for filtering
 - Slow radar rotation rate
 - Highest PRF (1304 Hz)
 - 250 m range resolution with 25 m range sampling
- Experiments with CASA X-band radars (Spring 2006)
- Develop signal processing strategy for mitigation of wind turbine clutter